Mathematical Problems in Climate Dynamics, CIMA + IFAECI Univ. of Buenos Aires, 2–13 November 2018

Basic Facts of GFD + Atmospheric LFV, Wind-driven Oceans, Paleoclimate & "Tipping Points"

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Please visit these sites for more info. <u>https://dept.atmos.ucla.edu/tcd, http://www.environnement.ens.fr/</u> and <u>https://www.researchgate.net/profile/Michael_Ghil</u>

Overall Outline

- Lecture I: Observations and planetary flow theory (GFD^(%))
- Lecture II: Atmospheric LFV^(*) & LRF^(**)
- ➡ Lecture III: EBMs⁽⁺⁾, paleoclimate & "tipping points"
 - Lecture IV: Nonlinear & stochastic models RDS^(*)
 - Lecture V: Advanced spectral methods–SSA^(±) et al.
 - Lecture VI: The wind-driven ocean circulation

- (%) GFD = Geophysical fluid dynamics
- (*) LFV = Low-frequency variability
- (**) LRF = Long-range forecasting
- (+) EBM = Energy balance model
- (*) RDS = Random dynamical system
- (±) SSA = Singular-spectrum analysis

Composite spectrum of climate variability

Standard treatement of frequency bands:

- 1. High frequencies white noise (or "colored")
- 2. Low frequencies slow evolution of parameters



** 27 years – Brier (1968, *Rev. Geophys.*)

F. Bretherton's "horrendogram" of Earth System Science



Earth System Science Overview, NASA Advisory Council, 1986

Climate models (atmospheric & coupled) : A classification



- unidirectional asynchronous, hybrid
- Full

Hierarchy: back-and-forth between the simplest and the most elaborate model, and between the models and the observational data

Motivation

- There's a lot of talk about "tipping points."
- It sounds threatening, like falling off a cliff: that's why we care!
- But what are they, and what do we know about them?
- Here's a **disambiguation page** (cf. Wikipedia), first.
- *Sociology*: "the moment of critical mass, the threshold, the boiling point" (Gladwell, 2000); a previously rare phenomenon becomes rapidly and dramatically more common.
- *Physics*: the point at which a system changes from a stable equilibrium into a new, qualitatively dissimilar equilibrium (throwing a switch, tilting a plank, boiling water, etc.).
- Climatology: "A climate tipping point is a somewhat ill-defined concept [...]"— so we'll try to actually define it better.

Catastrophe theory: branch of bifurcation theory in the study of dynamical systems; here, a tipping point is "a parameter value at which the set of equilibria abruptly change." → Let's see!

M. Gladwell (2000) *The Tipping Point: How Little Things Can Make a Big Difference.*T. M. Lenton *et al.* (2008) Tipping elements in the Earth's climate system, *PNAS*, v. **105**.

Rotating Convection: An Illustration



M. Ghil, P.L. Read & L.A. Smith (Astron. Geophys., 2010)

Outline, Tipping Points I

Elementary Bifurcation Theory and Variational Principle

1. Fixed Points

- linear stability
- non-linear stability and attractor basins
- 2. Saddle-node bifurcations
 - multiple branches of stationary solutions
 - linear stability
- 3. Bifurcations in 1-D
- 4. Non-linear stability and variational principle
 - variational principle in 0-D
 - variational principle in 1-D
- 5. Bistability and hysteresis

1. Fixed points, I

We start with a scalar ordinary differential equation (ODE) $\dot{x} = f(x; \mu)$

depending on the parameter μ .

Linear stability, $\mu = 1$. $f(x_0) = 0 \Rightarrow \dot{x} = 0 \Rightarrow x \equiv x_0$ – Fixed point (FP)

Consider an initial perturbation at t = 0: $x(0) = x_0 + \xi(0),$ $\dot{x} = \dot{x_0} + \dot{\xi} = \dot{\xi}$ $= f(x_0 + \xi) = f(x_0) + f'(x_0)\xi + O(\xi^2)$

For an infinitesimal perturbation $\xi(0) = \xi_0$ $\dot{\xi} = f'(x_0)\xi, \quad f'(x_0) = \lambda, \quad \dot{\xi} = \lambda\xi,$ $\Rightarrow \xi(t) = e^{\lambda t}\xi(0)$

1. Fixed points, II

If $\lambda < 0 \Rightarrow$ the fixed point (FP) is (linearly) stable

If $\lambda > 0 \Rightarrow$ the FP is (linearly) unstable

If $\lambda = 0 \Rightarrow$ the linear stability of the FP is neutral

Some basic features on FPs:

1. $f \in C^1, f \not\equiv 0$ on all sub-intervals: FPs are isolated (generic property)

2. Basins of attraction are open intervals (possibly semi-infinite)



2. Saddle-node bifurcations

How does the geometry of the solutions change when $\mu \neq \mu_0$, i.e. how do the number of the stability of the stationary solution change?

Let us start with the scalar case.



Let us now examine the nonlinear stability

3. Bifurcations in *n*-D

We studied the scalar case (n = 1). More generally, we have:

 $\dot{\mathbf{x}} = f(\mathbf{x}; \mu), \ f \in C(\Re^n \times \Re),$ with $\mathbf{x} \in \Re^n$ and $\mu \in \Re$.

The behavior is "almost" linear in all the phase-parameter space $\Re^n \times \Re$, except in the neighborhood of a few isolated points (x_c, μ_c) : these are bifurcation points, where the Jacobian matrix $L = (\partial f_i / \partial x_j)$ is singular, i.e. det L = 0

In the case n = 2, we can reduce to the normal form :

 $\dot{x_1} = \mu - x_1^2$ $\dot{x_2} = -\lambda x_2, \ \lambda > 0$

In the general case, the reduction gives :

$$\dot{x_1} = \mu - x_1^2$$

 $\dot{x_i} = -\lambda_i x_i, \ \lambda_i > 0, \ i = 2, ..., n$



This shape explains the "saddlenode bifurcation" terminology

4. Non-linear stability and variational principle

To deepen our understanding of stability, we have to examine the effect of larger perturbations.

a) Variational principle in 0-D

 $V(x) = -\int_{x} f(\xi) d\xi - \text{pseudo-potential}$ $\dot{x} = f(x) = -V'(x)$ $\dot{x}^{2} = -\frac{\partial V}{\partial x} \frac{\partial x}{\partial t} = -\dot{V}$



V will decrease along the ODE's trajectory as long as : $\dot{x} \neq 0 \Leftrightarrow V' \neq 0$

 $\dot{x} = 0$ if V reaches a minimum, a maximum, or a saddle-point.

Of course, only V = min is stable – nonlinearly.

With this result, we turn back to the saddle-node bifurcation:

$$\dot{x} = \mu - x^2$$

 $V(x;\mu) = -\mu x + x^3/3 + c(\mu)$

5. Bistability and hysteresis

The combination of two saddle-node bifurcations can create a hysteresis phenomenon (an *S*-shaped curve) :



 $\dot{x} = (\mu - 1) + (x + \frac{1}{2})^2$: the bottom-right bifurcation

Outline, EBMs

Energy Balance Models (EBMs)

- 1. Radiation Balance
 - 0-D
 - 1-D in the meridional direction
- 2. EBMs, formulation and analysis
 - formulation in 0-D and 1-D
 - linear stability in 0-D and 1-D
- 3. Bifurcations in 0-D and 1-D
- 4. Nonlinear stability and variational principle
 - variational principle in 0-D
 - variational principle in 1-D
- 5. Comparison with 3-D GCM
- 6. Bistability and hysteresis

The mean atmospheric circulation

Direct Hadley circulation

Observed circulation





Idealized view of the atmosphere's global circulation.*

Schematic diagram of the atmospheric global circulation.*

*From Ghil and Childress (1987), Ch. 4



Long-term equilibrium between incident (solar, ultra-violet + visible) radiation R_{in} and outgoing (terrestrial, infrared) radiation R_{out} dominates climate.

Refs. [1] Egyptian scribe (3000 B.C.) : "The Sun heats the Earth," Rosetta stone, II. 13–17. [2] Herodotus (484 - cca. 425 B.C.)





Earth's Global Energy Budget

K.E. Trenberth, J.T. Fasullo & J. Kiehl, 2009,

Bull. Amer. Meteorol. Soc., 90(3), 311–323.





D'après Kuo-Nan Liou, 1980: An Introduction to Atmospheric Radiation (fig. 8.19)

Energy balance models (EBMs)

Problem 5: Compute the energy balance of Earth's atmosphere.

References

- 1. Reserve slides to this lecture.
- 2. Ghil, M., and S. Childress, 1987: Ch. 10 in *Topics in Geophysical Fluid Dynamics: Atmospheric Dynamics, Dynamo Theory and Climate Dynamics*, Springer-Verlag, New York, 485 pp.
- 3. Liou, K.-N., 2002: *An Introduction to Atmospheric Radiation*, 2nd ed., Academic Press, 583 pp. (compare also 1st ed., 1980)





Transport atmosphérique et océanique d'énergie en fonction de la latitude

$$F(\phi) = a \int_0^{\phi} \cos(\varphi) [R_i(\varphi) - R_o(\varphi)] d\varphi$$

Energy-balance models (EBMs)

$$C\frac{\partial T}{\partial t} = R_i - R_o + D$$

- C local calorific capacity
- T local surface temperature
- R_i incident solar radiation
- R_o terrestrial radiation towards space
- D heat redistribution ('diffusion')

Comments:

1. C, R_i, R_o and D have to be calculated ("parameterized") according to T = T(x, t)

2. The model's main characteristic is $R_{\rm i}$ $R_i = Q(x) \{1 - \alpha(x, T)\}$ with α the local albedo.



0-D version (averaged over the globe)

$$C\frac{d\bar{T}}{dt} = R_i - R_o = Q\left\{1 - \alpha(\bar{T})\right\} - \sigma\bar{T}^4m(\bar{T})$$

- \overline{T} average surface temperature t — time (in thousands of years) Q — incident solar flux α — albedo C — calorific capacity σ — Stefan–Boltzmann constant
- m greenhouse effect factor

Comments:

 α depends on the ice and snow cover, on cloud cover, etc. (implicit variables). All is parameterized as a function of the explicit variable \overline{T} .



0-D EBM, I: Model solutions

We want to write **T** as: $T = T(t; T_0, Q, c, ...)$

Stationary solutions: $Q\{1 - \alpha(T)\} - \sigma T^4 = 0$



What happens if the sun "blinks" and $T = T_1 + \Delta T$? We have to go back to the original equation, which depends on time.

0-D EBM, II: Stability condition

$$C\partial_t T = R_i - R_o = f(T)$$
$$R_i = Q\{1 - \alpha(T)\}$$
$$R_o = A + BT$$

We set
$$T = T_j + \theta$$
:
 $f(T_j) = 0$,
 $f(T) = f(T_j) + f'(T_j)\theta + \dots$



Let's define $\lambda_j \equiv f'(T_j)/c$ $\partial_t \theta = \lambda_j \theta \Rightarrow \theta = e^{\lambda_j t} \theta_0$ If $\lambda_j < 0$ stable; if $\lambda_j > 0$ unstable. **Comment:** in the 1-D case $\lambda_j o \lambda_j^{(0)};$ $\lambda_j \sim 1/c$

0-D EBM, III: Changes in parameters

What happens if the insolation parameter μ changes, i.e., the "solar constant" changes? This may represent a change in solar luminosity, orbital parameters or in the optical properties of the atmosphere.

✤The model's three "climates" shift in value and, possibly, $c_T \frac{\mathrm{d}\overline{T}}{\mathrm{d}t} = R_{\mathrm{i}} - R_{\mathrm{o}}$ in number. $\mu Q_0, \mu < 1$ Energy Ŧ,

1-D version ('classic' EBM)

$$C(x)T_t = R_i - R_o + D$$

T - temperature Boundary conditions: x - latitudinal coordinate x = 0 Pole (North) $\tilde{T}(x)$ - the observed climate x = 1 Equator

Boundary conditions: $T_x(0) = T_x(1) = 0$ x = 0 Pole (North) x = 1 Equator

$$R_{i} = Q(x)\{1 - \alpha\}$$

= $Q(x)\{1 - b(x) + c_{1}T\}_{c}$
 $R_{o} = \sigma T^{4}\{1 - m \tanh(c_{3}T^{6})\}$



$$D = \frac{1}{\sin\frac{\pi x}{2}} \partial_x \sin\frac{\pi x}{2} \{k(x) + k_s(x)g(\tilde{T})\}T_x$$

Questions: 1. Stationary solutions ('climates')?
2. Stability?
3. Perturbation & bifurcation?
$$Q \rightarrow \mu Q$$
 ($\mu = 1$)



1-D EBM: Bifurcation diagram



5. Bistability and hysteresis

The combination of two saddle-node bifurcations can create a hysteresis phenomenon (an *S*-shaped curve) :



Elementary bifurcation problems for PDEs

Problem 6: Compute the saddle-node bifurcation for the reaction-diffusion problem

$$u_t = ku_{xx} + \mu(1 - u^2)$$

with suitable boundary conditions on the interval

 $0 \le x \le 1.$

Energy Balance Models (EBMs) Budyko, Sellers and Held-Suarez-North

10.2. Energy-Balance Models (EBMs): Multiple Equilibria

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Table 10.1. Comparison of Budyko's and Sellers' models.

Heat Flux	Budyko	Sellers
R _i = Q(1 - α(T)) Absorbed solar radia- tion, as a function of ice-albedo feedback	$\begin{split} \text{Step-function albedo} \\ \alpha &= \left\{ \begin{array}{l} \alpha_{\text{M}}, \ \text{T} < \text{T}_{\text{S}}, \\ \alpha_{\text{m}}, \ \text{T} \geq \text{T}_{\text{S}}, \\ \alpha_{\text{m}}, \ \text{T} \geq \text{T}_{\text{S}}, \\ \end{array} \right. \\ \alpha_{\text{M}} &> \alpha_{\text{m}}, \\ \text{T}_{\text{L}} &\leq \text{T}_{\text{S}} \leq \text{T}_{\text{U}} \end{split}$	$ \begin{array}{l} \text{Ramp-function albedo} \\ \alpha = \left\{ \begin{array}{c} \alpha_{M}, & T < T_{\hat{\ell}} \\ & \\ \alpha_{M}, & T - T_{\hat{\ell}} \\ \alpha_{M} - \frac{T - T_{\hat{\ell}}}{T_{u} - T_{\hat{\ell}}} (\alpha_{M} - \alpha_{m}) \\ & T_{\hat{\ell}} \leq T < T_{u}, \\ \alpha_{m}, & T_{u} \leq T^{u}, \end{array} \right. $
R _O Outgoing IR radiation	Linear, empirical A + BT	Stefan-Boltzmann law with greenhouse effect $\sigma T^{4} \{1 - m \tanh(T^{6}/T_{0}^{6})\}$
∇·F Horizontal flux divergence	Newtonian cooling $\kappa\{T(\phi) - \overline{T}\}$	Eddy-diffusive $\nabla \cdot \{k(\phi) \nabla T(\phi)\}$

2nd column: Budyko (1968, 1969)

3rd column: Sellers (1969)

In red:

the "mixed" version of Held & Suarez (1974) and North (1975a, b)

Climate sensitivity to insolation in a General Circulation Model (GCM)

"As stated in the Introduction, it is not, however, reasonable to conclude that the present results are more reliable than the results from the onedimensional studies mentioned above simply because our model treats the effect of transport explicitly rather than by parameterization."*

"Nevertheless, it seems to be significant that both the onedimensional and three- dimensional models yield qualitatively similar results in many respects."*



Area-mean temperatures for various model levels, as well as a mass-weighted mean temperature for the total model atmosphere. Based on 4 GCM runs: control, –4%, –2% and +4%. Units are in degrees K.

^{*} From Wetherald and Manabe, 1975, *J. Atmos. Sci.*, **32**, 2044–2059.

Snowball Earth — Erstwhile a "theory"; now a "fact"?



https://www.nsf.gov/news/news_images.jsp?cntn_id=116410&org=NSF

Double-well potential in 2-D

1-D EBM of Budyko-Sellers-North, cf. Held & Suarez (Tellus, 1974); North et al. (JAS, 1979).

Taking x = sin(latitude) and $k(x, T) = k_0$, We get the semi-linear parabolic PDE

 $CT_t = [k_0(1 - x^2)T_x]_x + Q(x)[1 - \alpha(T)] - I(T)$

which yields the variational principle:



Distance to "tipping points"?

 \vdash

Femperature,

Slightly modified 0-D EBM (Zaliapin & Ghil, NPG, 2010)

$$c\dot{T} = \mu Q_0 (1 - \alpha(T)) - \sigma T^4 [1 - m \tanh((T/T_0) + c_1 + c_2) - \frac{1 - \tanh[\kappa(T - T_c)]}{2}$$

 T_c is the ice-margin temperature, while κ is an extra "Budyko-vs.-Sellers" parameter





Concluding remarks, I

- Tipping points and bifurcations: multiple equilibria and rapid transitions between them.
- Prediction of the transitions? To follow.
- Transitions between more general types of behavior limit cycles, strange attractors — likewise to follow.

Some general references

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